Stability of high frequency amplifiers via singularities of the Harmonic Transfer Function Workshop ERNSI

L.BARATCHART, S.FUEYO and J-B.POMET

27 May 2021

Innia

Explaining the title

■ Dynamical system with periodic solution ⇒ Is it locally stable?

■ Dynamical system with periodic solution ⇒ Is it locally stable?

Delay or 1-D Hyperbolic PDE.

- Dynamical system with periodic solution ⇒ Is it locally stable?
- Delay or 1-D Hyperbolic PDE.
- Characterization in the frequency domain.

- Dynamical system with periodic solution ⇒ Is it locally stable?
- Delay or 1-D Hyperbolic PDE.
- Characterization in the frequency domain.
- Nonlinear electric circuit containing transmission lines.





2 Circuits without transmission lines

3 General circuits containing lossless transmission lines



2 Circuits without transmission lines

3 General circuits containing lossless transmission lines

Inside

An amplifier is made of interconnected

- 1 resistors, inductors, capacitors,
- 2 diodes/transistors (active component),
- **3** lossless transmission lines inducing delays.
- Forcing periodic input (large signal functioning)
- ▶▶ periodic solution in the amplifier.



Motivation

- Amplifiers at high frequency are ubiquitous (Cell phones, relays...). They need to be quick to design.
- Required Computer-assisted design (CAD) and simulation.
- time domain inefficient \Rightarrow Need to work in frequency domain.
- Need for a tool to predict stability/unstability from the frequency domain data.

Harmonic Balance: a numerical heuristic

The Harmonic Balance method, through Fourier development, Laplace transform and fixed point methods permits to :

- approximate a periodic solution of the circuit,
- Inearize the (equations of) circuit around the periodic solution.
- compute the frequency response to a small periodic signal which disturbs the linearized circuit.

Harmonic balance method : Numerically implemented. (ADS, MWO and Spectre softwares)





►► Frequency response of the linearized system to a perturbation signal: input-output system

►► Frequency response of the linearized system to a perturbation signal: input-output system

▶▶ if the input is $e^{i\omega t}$ then the output is $G(i\omega, t)e^{i\omega t}$

►► Frequency response of the linearized system to a perturbation signal: input-output system

- ▶▶ if the input is $e^{i\omega t}$ then the output is $G(i\omega, t)e^{i\omega t}$
- ►► Rational approximation tools used on the Fourier development of $G(i\omega, \cdot)$ (Harmonic Transfer Function)

►► Frequency response of the linearized system to a perturbation signal: input-output system

▶▶ if the input is $e^{i\omega t}$ then the output is $G(i\omega, t)e^{i\omega t}$

►► Rational approximation tools used on the Fourier development of $G(i\omega, \cdot)$ (Harmonic Transfer Function)

►► Implementation STAN tool software or see method in the paper [CSO^+18].

►► Frequency response of the linearized system to a perturbation signal: input-output system

▶▶ if the input is $e^{i\omega t}$ then the output is $G(i\omega, t)e^{i\omega t}$

►► Rational approximation tools used on the Fourier development of $G(i\omega, \cdot)$ (Harmonic Transfer Function)

▶▶ Implementation STAN tool software or see method in the paper [CSO^+18].

Our focus in this talk:

- Structure of the Harmonic Transfer Function: analytic operator valued.
- its singularities, are they poles?
- links with local stability in the time domain.



2 Circuits without transmission lines

3 General circuits containing lossless transmission lines

Resistors, transistors, inductors, capacitors and forcing periodic signal

+

Kirshhoff's laws.

Assumption: Existence of a *T*-periodic solution.

Resistors, transistors, inductors, capacitors and forcing periodic signal

Kirshhoff's laws.

+

Assumption: Existence of a *T*-periodic solution. Linearization around periodic solution:

$$\frac{dx(t)}{dt} = A(t)x(t),$$

x: state of the circuit (currents or voltages),

Resistors, transistors, inductors, capacitors and forcing periodic signal

Kirshhoff's laws.

+

Assumption: Existence of a *T*-periodic solution. Linearization around periodic solution:

$$\frac{dx(t)}{dt} = A(t)x(t),$$

x: state of the circuit (currents or voltages),

Paradigm: Exponential stability of the origin of the linearized equation implies local stability of the periodic solution.

No transmission lines. Time-invariant case

Dynamical system:

$$\frac{dx(t)}{dt} = Ax(t),$$

x: state of the circuit (current or voltage).

No transmission lines. Time-invariant case

Dynamical system:

$$\frac{dx(t)}{dt} = Ax(t),$$

x: state of the circuit (current or voltage).

Definition

The origin of the system is exponentially stable if there exists γ , K positive such that:

$$||x(t)|| \leq Ke^{-\gamma t} ||x(0)||,$$

 $x(\cdot)$ solution of the system.

No transmission lines. Time-invariant case

Dynamical system:

$$\frac{dx(t)}{dt} = Ax(t),$$

x: state of the circuit (current or voltage).

Definition

The origin of the system is exponentially stable if there exists γ , K positive such that:

 $||x(t)|| \le Ke^{-\gamma t} ||x(0)||,$

 $x(\cdot)$ solution of the system.

Theorem (classical)

Origin exp. stable if and only if the real part of the eigenvalues of A are strictly negative.

Time-invariant case

Input-output system :

$$\begin{cases} \frac{d}{dt}y(t) = Ay(t) + Bu(t) \\ z(t) = Cy(t) + Du(t), t \ge 0. \end{cases}$$

Input-output system :

$$\begin{cases} \frac{d}{dt}y(t) = Ay(t) + Bu(t) \\ z(t) = Cy(t) + Du(t) , t \ge 0. \end{cases}$$

Transfer function : $H(s) := C(sI_n - A)^{-1}B + D$. It satisfies the property: Z(s) = H(s)U(s), $Z(\cdot)$, $U(\cdot)$ Laplace transform of $z(\cdot)$, $u(\cdot)$. Input-output system :

$$\begin{cases} \frac{d}{dt}y(t) = Ay(t) + Bu(t) \\ z(t) = Cy(t) + Du(t), t \ge 0. \end{cases}$$

Transfer function : $H(s) := C(sI_n - A)^{-1}B + D$. It satisfies the property: Z(s) = H(s)U(s), $Z(\cdot)$, $U(\cdot)$ Laplace transform of $z(\cdot)$, $u(\cdot)$.

Theorem (classical)

If the system is observable and controllable, the singularities of the transfer function are poles and are the eigenvalues of A. Therefore the system is exponentially stable if and only if H(s) analytic in the closed right half plane.

Periodic case: Nonlinear

$$rac{dx(t)}{dt} = A(t)x(t), \ T > 0$$
 periodic.

Periodic case: Nonlinear

$$rac{dx(t)}{dt} = A(t)x(t), \ T > 0$$
 periodic.

Definition

The origin of the system is exponentially stable if there exists γ , K positive such that:

$$||x(t)|| \le Ke^{-\gamma t} ||x(0)||,$$

 $x(\cdot)$ solution of the system.

Periodic case: Nonlinear

$$rac{dx(t)}{dt} = A(t)x(t), \ T > 0$$
 periodic.

Definition

The origin of the system is exponentially stable if there exists γ , K positive such that:

$$||x(t)|| \le Ke^{-\gamma t} ||x(0)||,$$

 $x(\cdot)$ solution of the system.

 \Rightarrow Eigenvalues of A(t) do not give the exponential stability of the origin anymore.

Periodic case: Monodromy operators

Periodic ODE \Rightarrow Subsumed under **Floquet Theory**.

Periodic case: Monodromy operators

Periodic ODE \Rightarrow Subsumed under **Floquet Theory**. We introduce the fundamental solution $X(t, t_0)$ which satisfies :

$$egin{array}{rcl} \displaystylerac{d}{dt}X(t,t_0)&=&A(t)X(t,t_0),\ t\geq t_0,\ X(t_0,t_0)&=&\mathit{Id},\ ext{for all}\ t_0\in\mathbb{R}. \end{array}$$

Definition (monodromy operators)

.

The monodromy operators of the system are the operator $X(T + t_0, t_0)$ for t_0 real.

Periodic ODE \Rightarrow Subsumed under **Floquet Theory**. We introduce the fundamental solution $X(t, t_0)$ which satisfies :

$$egin{array}{rcl} \displaystylerac{d}{dt}X(t,t_0)&=&A(t)X(t,t_0),\ t\geq t_0,\ X(t_0,t_0)&=&\mathit{Id},\ ext{for all }t_0\in\mathbb{R}. \end{array}$$

Definition (monodromy operators)

The monodromy operators of the system are the operator $X(T + t_0, t_0)$ for t_0 real.

Theorem (classical)

Origin exp. stable if and only if the spectrum of the monodromy X(T, 0) operator is strictly included in the unit disk.

Input-output system:

$$\begin{cases} \frac{d}{dt}y(t) = A(t)y(t) + B(t)u(t)\\ z(t) = C(t)y(t) + D(t)u(t), \ t \ge 0, \end{cases}$$

Input-output system:

$$\begin{cases} \frac{d}{dt}y(t) = A(t)y(t) + B(t)u(t)\\ z(t) = C(t)y(t) + D(t)u(t), \ t \ge 0, \end{cases}$$

Fourier series:

$$\begin{cases} \frac{d}{dt}y(t) = \sum_{k=-\infty}^{\infty} a_k e^{i\omega_0 kt} y(t) + \sum_{k=-\infty}^{\infty} b_k e^{i\omega_0 kt} u(t), \\ z(t) = \sum_{k=-\infty}^{\infty} c_k e^{i\omega_0 kt} y(t) + \sum_{k=-\infty}^{\infty} d_k e^{i\omega_0 kt} u(t), \end{cases}$$

 $\omega_0 := 2\pi/T.$

Input-output system:

$$\begin{cases} \frac{d}{dt}y(t) = A(t)y(t) + B(t)u(t)\\ z(t) = C(t)y(t) + D(t)u(t), \ t \ge 0, \end{cases}$$

Fourier series:

$$\begin{cases} \frac{d}{dt}y(t) = \sum_{k=-\infty}^{\infty} a_k e^{i\omega_0 kt} y(t) + \sum_{k=-\infty}^{\infty} b_k e^{i\omega_0 kt} u(t), \\ z(t) = \sum_{k=-\infty}^{\infty} c_k e^{i\omega_0 kt} y(t) + \sum_{k=-\infty}^{\infty} d_k e^{i\omega_0 kt} u(t), \end{cases}$$

 $\omega_0 := 2\pi/T$. Fourier series + Laplace transform \Rightarrow Infinite time-invariant system.

Harmonic Transfer Function

$$Z(s) = ? \begin{pmatrix} \vdots \\ U(s + i\omega_0) \\ U(s) \\ U(s - i\omega_0) \\ \vdots \end{pmatrix}$$

Harmonic Transfer Function

There exists $H(\cdot)$ infinite matrix such that:

$$\begin{pmatrix} \vdots \\ Z(s+i\omega_0) \\ Z(s) \\ Z(s-i\omega_0) \\ \vdots \end{pmatrix} = H(s) \begin{pmatrix} \vdots \\ U(s+i\omega_0) \\ U(s) \\ U(s-i\omega_0) \\ \vdots \end{pmatrix}$$

Definition

The infinite matrix $H(s) := L_C [D_{\omega_0}(s) - L_A]^{-1} + L_D$ is called the **Harmonic Transfer Function** (HTF) matrix. (Wereley)

Where
$$D_{\omega_0}(s) := Diag(\cdots, s + i\omega_0, s, s - i\omega_0, \cdots)$$
 and $L_A := (a_{j-i})_{i,j\in\mathbb{Z}}, L_B := (b_{j-i})_{i,j\in\mathbb{Z}}, L_C := (c_{j-i})_{i,j\in\mathbb{Z}}$ and $L_D := (d_{j-i})_{i,j\in\mathbb{Z}}$.

 HTF defines an operator valued analytic map (values: continuous ops l²(ℤ) → l²(ℤ))

- HTF defines an operator valued analytic map (values: continuous ops l²(ℤ) → l²(ℤ))
- ►► A priori HTF can have many kind of singularities.

- HTF defines an operator valued analytic map (values: continuous ops l²(ℤ) → l²(ℤ))
- ►► A priori HTF can have many kind of singularities.
 - its entries are matrix complex valued analytic maps

- HTF defines an operator valued analytic map (values: continuous ops l²(ℤ) → l²(ℤ))
- ►► A priori HTF can have many kind of singularities.
 - its entries are matrix complex valued analytic maps

►► Can be a singularity of the *HTF*, but what is the link with the singularities of the entries of the *HTF*?

Let H(s) an operator valued analytic map (values: continuous ops $l^2(\mathbb{Z}) \to l^2(\mathbb{Z})$) on an open set S.

■ $s_0 \in \overline{S}$ is a singularity of $H(\cdot)$ if $H(\cdot)$ does not admit an analytic continuation in s_0 . In particular if $H(s_0)$ is not a bounded operator from l^2 to l^2 then it is a singularity.

Let H(s) an operator valued analytic map (values: continuous ops $l^2(\mathbb{Z}) \to l^2(\mathbb{Z})$) on an open set S.

- $s_0 \in \overline{S}$ is a singularity of $H(\cdot)$ if $H(\cdot)$ does not admit an analytic continuation in s_0 . In particular if $H(s_0)$ is not a bounded operator from l^2 to l^2 then it is a singularity.
- However each coefficient of the infinite matrix can be defined in s₀.

Let H(s) an operator valued analytic map (values: continuous ops $l^2(\mathbb{Z}) \to l^2(\mathbb{Z})$) on an open set S.

- $s_0 \in \overline{S}$ is a singularity of $H(\cdot)$ if $H(\cdot)$ does not admit an analytic continuation in s_0 . In particular if $H(s_0)$ is not a bounded operator from l^2 to l^2 then it is a singularity.
- However each coefficient of the infinite matrix can be defined in s₀.

As example s_0 is an essential singularity:

1

$$\lim_{n\to+\infty}\|H(s_0)x_n\|=+\infty,$$

where $||x_n|| = 1$ and all the coefficients of $H(s_0)$ exists and are finite.

Dwelling on Floquet Theory, we have:

Theorem (After Suarez and Quéré 02 or Louarroudi 14 for example)

Each element of the HTF is a meromorphic function. And its poles are included (possibly strictly) in the set of the complex numbers of the form $\frac{\ln(\zeta)+2i\pi k}{T}$ for all $k \in \mathbb{Z}$ and where ζ is an eigenvalue of the monodromy operator.

Theorem (classical)

Assume the system is observable and controllable, then for all ζ an eigenvalue of the monodromy operator there exists k integer such that H(s), and one of its entries, has a pole in $\frac{\ln(\zeta)+2i\pi k}{T}$. Therefore origin exp. stable if and only if H(s) analytic in the closed right half plane.



2 Circuits without transmission lines

3 General circuits containing lossless transmission lines



2 Circuits without transmission lines

3 General circuits containing lossless transmission lines

■ Nonlinear circuit + lossless transmission lines

Lossless transmission lines

- Nonlinear circuit + lossless transmission lines
- Lossless transmission lines → Telegrapher's equations (1-D hyperbolic) PDE → Resolved form → Delays equations.

Lossless transmission lines

- Nonlinear circuit + lossless transmission lines
- Lossless transmission lines \rightarrow Telegrapher's equations (1-D hyperbolic) PDE \rightarrow Resolved form \rightarrow Delays equations.
- Existence of a *T*-periodic solution.

Lossless transmission lines

- Nonlinear circuit + lossless transmission lines
- Lossless transmission lines → Telegrapher's equations (1-D hyperbolic) PDE → Resolved form → Delays equations.
- Existence of a *T*-periodic solution.

Linearization around periodic solution:

$$\left\{ egin{array}{l} rac{dx(t)}{dt} = A_1(t)x(t) + \sum\limits_{i=0}^N B_{1,i}(t)y(t- au_i) \ y(t) = \sum\limits_{i=1}^N B_{2,i}(t)y(t- au_i) + A_2(t)x(t), \ t \geq t_0. \end{array}
ight.$$

For electronic applications: continuous solution and C^0 stability are needed.

However Fourier development of the system: L^2 solutions needed.

Anyway: L^2 stability is equivalent to the C^0 stability.

$$\left\{ egin{array}{l} rac{dx(t)}{dt} = A_1(t)x(t) + \sum\limits_{i=0}^N B_{1,i}(t)y(t- au_i) \ y(t) = \sum\limits_{i=1}^N B_{2,i}(t)y(t- au_i) + A_2(t)x(t), \ t \geq t_0, \end{array}
ight.$$

$$\left\{ egin{array}{l} rac{dx(t)}{dt} = A_1(t)x(t) + \sum\limits_{i=0}^N B_{1,i}(t)y(t- au_i) \ y(t) = \sum\limits_{i=1}^N B_{2,i}(t)y(t- au_i) + A_2(t)x(t), \ t \geq t_0, \end{array}
ight.$$

• State space: $\mathcal{Y}L^2 := \mathbb{R}^n \times L^2([-\tau_N, 0], \mathbb{R}^k).$

$$\left\{ egin{array}{l} rac{dx(t)}{dt} = A_1(t)x(t) + \sum\limits_{i=0}^N B_{1,i}(t)y(t- au_i) \ y(t) = \sum\limits_{i=1}^N B_{2,i}(t)y(t- au_i) + A_2(t)x(t), \ t \geq t_0, \end{array}
ight.$$

State space: 𝔅L² := ℝⁿ × L²([−τ_N, 0], ℝ^k).
 Solution operator U(t, t₀) : 𝔅L² → 𝔅L²

$$\left\{ egin{array}{l} rac{dx(t)}{dt} = A_1(t)x(t) + \sum\limits_{i=0}^N B_{1,i}(t)y(t- au_i) \ y(t) = \sum\limits_{i=1}^N B_{2,i}(t)y(t- au_i) + A_2(t)x(t), \ t \geq t_0, \end{array}
ight.$$

- State space: $\mathcal{Y}L^2 := \mathbb{R}^n \times L^2([-\tau_N, 0], \mathbb{R}^k).$
- Solution operator $U(t, t_0) : \mathcal{Y}L^2 \to \mathcal{Y}L^2$
- Monodromy operator U(T, 0)

$$\begin{cases} \frac{dx(t)}{dt} = A_1(t)x(t) + \sum_{i=0}^{N} B_{1,i}(t)y(t-\tau_i) \\ y(t) = \sum_{i=1}^{N} B_{2,i}(t)y(t-\tau_i) + A_2(t)x(t), \ t \ge t_0, \end{cases}$$

- State space: $\mathcal{Y}L^2 := \mathbb{R}^n \times L^2([-\tau_N, 0], \mathbb{R}^k).$
- Solution operator $U(t, t_0) : \mathcal{Y}L^2 \to \mathcal{Y}L^2$
- Monodromy operator U(T, 0)

$$\left. \begin{array}{c} L^2 \text{ exponential} \\ stability \end{array} \right\} \Leftrightarrow \left\{ \begin{array}{c} Sp(U(T,0)) \text{ included in} \\ \text{ disc of radius } r < 1 \end{array} \right.$$

$$egin{aligned} & rac{dx(t)}{dt} = A_1(t)x(t) + \sum\limits_{i=0}^N B_{1,i}(t)y(t- au_i) \ & y(t) = \sum\limits_{i=1}^N B_{2,i}(t)y(t- au_i) + A_2(t)x(t), \ t \geq t_0, \end{aligned}$$

- State space: $\mathcal{Y}L^2 := \mathbb{R}^n \times L^2([-\tau_N, 0], \mathbb{R}^k).$
- Solution operator $U(t, t_0) : \mathcal{Y}L^2 \to \mathcal{Y}L^2$
- Monodromy operator U(T, 0)

$$\left. \begin{array}{c} L^2 \text{ exponential} \\ stability \end{array} \right\} \Leftrightarrow \left\{ \begin{array}{c} Sp(U(T,0)) \text{ included in} \\ \text{ disc of radius } r < 1 \end{array} \right.$$

High frequency limit system :

$$\left\{egin{array}{l} x(t)=0 \ y(t)=\sum\limits_{i=1}^N B_{2,i}(t)y(t- au_i), \ t\geq t_0, \end{array}
ight.$$

- State space: $\mathcal{Y}\widetilde{L}^2 := \{0_n\} \times L^2([-\tau_N, 0], \mathbb{R}^k).$
- Solution operator $V(t, t_0) : \mathcal{Y}\tilde{L}^2 \to \mathcal{Y}\tilde{L}^2$.
- Monodromy operator V(T, 0).

$$\left. \begin{array}{c} L^2 \text{ exponential} \\ stability \end{array} \right\} \Leftrightarrow \left\{ \begin{array}{c} Sp(V(T,0)) \text{ included in} \\ \text{disc of radius } r < 1 \end{array} \right.$$

Lemma

We have :

$$U(t, t_0) = V(t, t_0)P + K(t, t_0), \ t \ge t_0$$

with $K(t, t_0)$ compact operator $\mathcal{Y}L^2 \to \mathcal{Y}L^2$ for all t, t_0 and P the canonical projection $\mathcal{Y}L^2 \to \mathcal{Y}\tilde{L}^2$.

Lemma

We have :

$$U(t, t_0) = V(t, t_0)P + K(t, t_0), \ t \ge t_0$$

with $K(t, t_0)$ compact operator $\mathcal{Y}L^2 \to \mathcal{Y}L^2$ for all t, t_0 and P the canonical projection $\mathcal{Y}L^2 \to \mathcal{Y}\tilde{L}^2$.

Theorem (classical)

A compact perturbation does not change the essential spectrum and it can add only point spectrum, i.e. eigenvalues.

If the high frequency system is L^2 exponentially stable then the monodromy operator U(T,0) possesses at most a finite number of eigenvalues ζ_1, \dots, ζ_n outside a disk of a radius strictly less than 1.

If the high frequency system is L^2 exponentially stable then the monodromy operator U(T,0) possesses at most a finite number of eigenvalues ζ_1, \dots, ζ_n outside a disk of a radius strictly less than 1.

 \Rightarrow High frequency system dissipates energy

If the high frequency system is L^2 exponentially stable then the monodromy operator U(T,0) possesses at most a finite number of eigenvalues ζ_1, \dots, ζ_n outside a disk of a radius strictly less than 1.

⇒ High frequency system dissipates energy (BFLP21)⇒ L^2 exp. stability of the high frequency system. It is a reasonable assumption for electric circuits.

If the high frequency system is L^2 exponentially stable then the monodromy operator U(T,0) possesses at most a finite number of eigenvalues ζ_1, \dots, ζ_n outside a disk of a radius strictly less than 1.

⇒ High frequency system dissipates energy (BFLP21)⇒ L^2 exp. stability of the high frequency system. It is a reasonable assumption for electric circuits. ⇒ Instability of the general linear system is governed just by a finite number of eigenvalues.

Input-Output system

$$\begin{cases} \frac{dx(t)}{dt} = A_1(t)x(t) + \sum_{i=0}^{N} B_i^1(t)y(t-\tau_i) + C_1(t)u(t) \\ y(t) = \sum_{i=1}^{N} B_i^2(t)y(t-\tau_i) + A_2(t)x(t) + C_2(t)u(t) \\ z(t) = \sum_{i=1}^{N} B_i^3(t)y(t-\tau_i) + A_3(t)x(t) + C_3(t)u(t), \ t \ge 0, \end{cases}$$

- x(t), y(t), z(t) = 0 for t < 0,
- Input $u \in L^2_{loc}([0, +\infty), \mathbb{R})$ current perturbation, output z the voltage,
- All coefficients are *T periodic*.

Harmonic Transfer Function

$$\begin{pmatrix} \vdots \\ Z(s+i\omega_0) \\ Z(s) \\ Z(s-i\omega_0) \\ \vdots \end{pmatrix} = H(s) \begin{pmatrix} \vdots \\ U(s+i\omega_0) \\ U(s) \\ U(s-i\omega_0) \\ \vdots \end{pmatrix}$$

- HTF is an operator valued analytic map (values: continuous ops l²(ℤ) → l²(ℤ))
- its entries are complex valued analytic maps

Define $z_{j,k} = \frac{ln(\zeta_j)+2ik\pi}{T}$ for j in $\{1...n\}$, k in \mathbb{Z} . Fundamental structure HTF for high dissipative amplifiers

Theorem

In the half space $\{s \in \mathbb{C}, \Re(s) \geq \gamma\}$ for some $\gamma < 0$,

- H is a meromorphic operator l²(Z) → l²(Z) whose poles are contained in {z_{j,k}, j ∈ {1...n}, k ∈ Z}.
- Under observability/controllability assumptions, for all j, there is at least a k such that z_{j,k} is one pole of H, and also a pole of one entries of the HTF.

If no entry of the HTF has poles in right half plane, we have the exponential C^0 stability.

Singularities of the HTF in the left right half plane?

- High frequency dissipative circuit ⇒ HTF meromorphic right half plane.
- Rational tools sometimes performes rational approximation on all the complex plane.
- Needs to know if there is just poles in the left half plane?

Simple example (Brayton 1976)



Input: uoutput: $z = v_1$

Theorem

If $T/\tau_1 \notin \mathbb{Q}$ and the system is observable, all points of a certain vertical line in the left-half plane are essential singularities of the HTF, as an operator valued analytic map.

But are they singularities for some entries of the HTF ?

Thank You!